University of São Paulo – USP Department of Physics and Mathematics

HUMAN NAVIGATION, MEG & fMRI RESULTS



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Navigation System

- What Defines Navigation?
- Higher Cognitive Process
- Hippocampus



"Place Cells" *

"Head Direction Cells" **

Rationale for an MEG and fMRI study

- ✓ Non-invasive
- Excellent spatiotemporal resolution
- Possibility of sources localization
- Include appropriate control studies
- ✓ Ability to extend the duration of the studies

Task Design

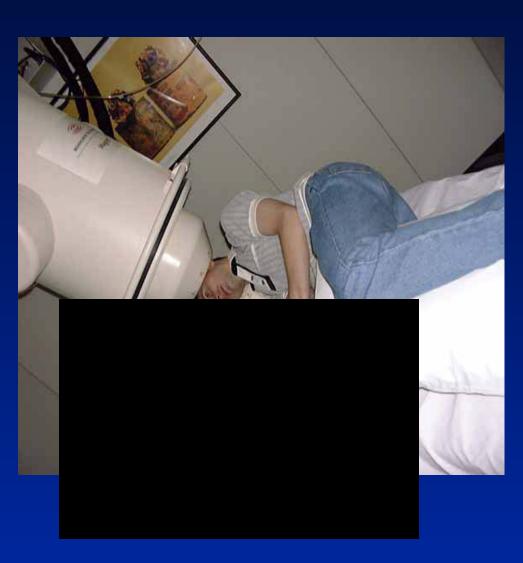
Virtual Reality City

11 Subjects

2x37 Channel 1st Gradiometers
Covering Temporal Hemispheres

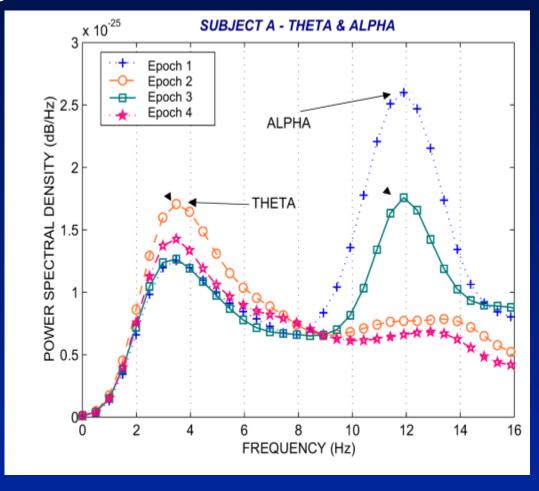
Parse recording into 4 epochs:

- 1) Base Line
- 2) Navigate before the Block*
- 3) Stop & Visualize path
- 4) Resume navigation*



Power Spectrum Density

- Power Spectral Density
 - Artifact rejection:
 - Blinking
 - Heart
 - Window FFT:
 - Type : Hanning
 - Resolution
 - · Aprox. 1 Sec.
 - Overlapping
 - None



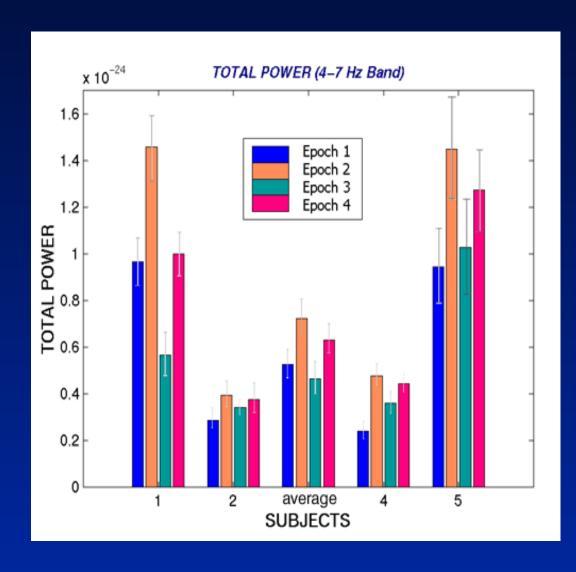
Theta band (4 - 7 Hz)

- Classical 4 Hz 7 Hz
- Average of 4 Runs
- Low theta power

epoch 1 & 3

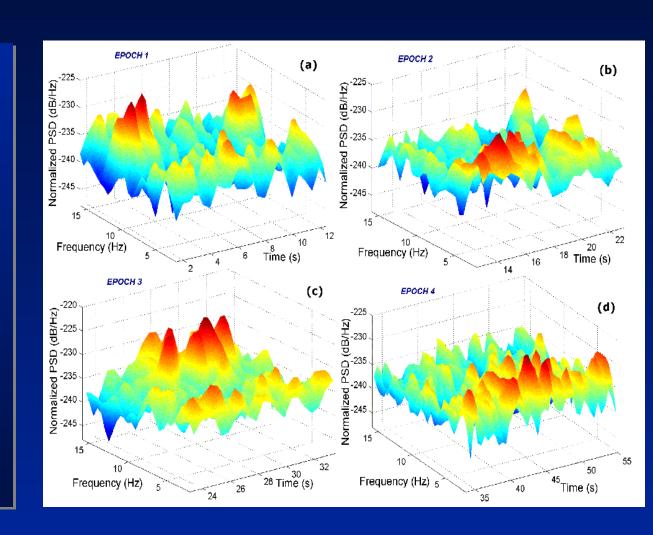
High theta power

epoch 2 & 4



Spectrogram

- Smooth α to θ transitions
- Epochs 1 & 3
 - Theta dominance
- Epochs 2 & 4
 - Alpha dominance



Localization - MSI

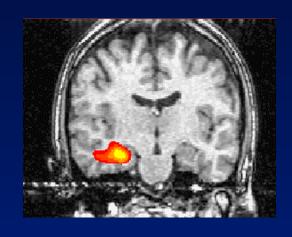
Simple Model Dipole

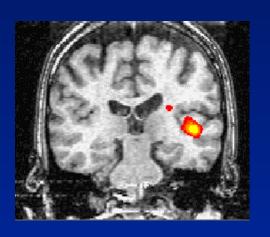
Dipole Density Plot

Gaussian filter

2 mm resolution

Main AreasSuperior temporal GyrusDeeper temporal structures

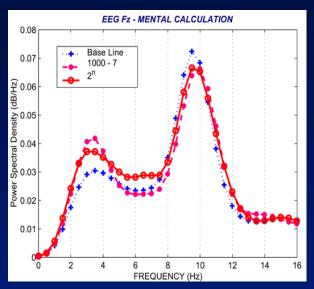


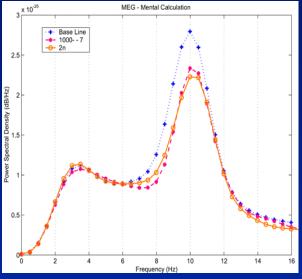


Control Studies

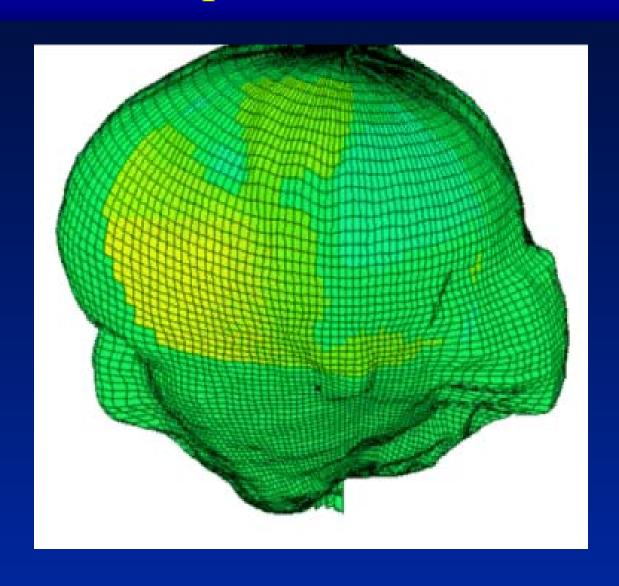
- ⇒ MEG probe positioning
 - Temporal Areas
- ⇒ 3 Different control studies
 - ⇒ Frontal Midline Theta

 - No increase in the MEG
 - → Motor Task
 - No increase in the MEG
 - Passive viewing
 - No increase in the MEG



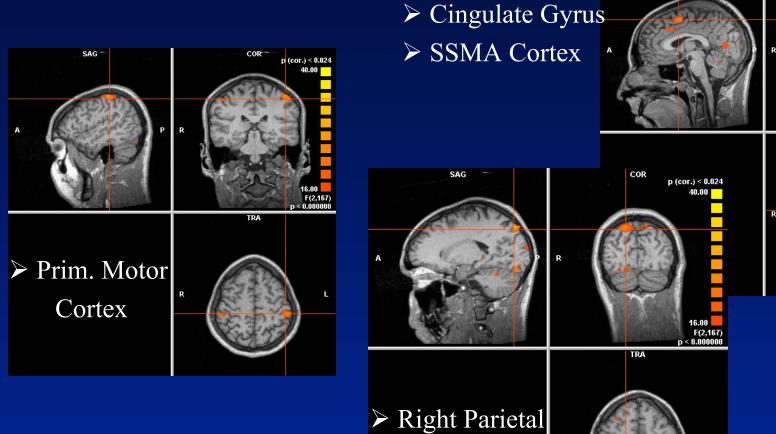


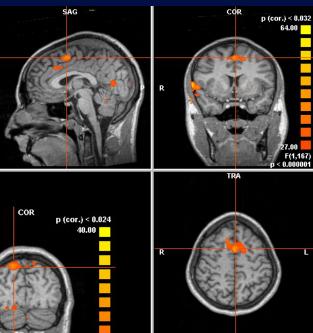
Dipole Pattern



fMRI: Preliminary Results

Cortex





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